

Relation between \underline{S} and \underline{Z}

$$\underline{V} = \underline{Z}\underline{I}$$

$$\underline{R}^{\frac{1}{2}}(\underline{a} + \underline{b}) = \underline{Z}\underline{R}^{-\frac{1}{2}}(\underline{a} - \underline{b})$$

$$\underline{a} + \underline{b} = \underline{R}^{\frac{1}{2}}\underline{Z}\underline{R}^{-\frac{1}{2}}(\underline{a} - \underline{b}) = \underline{Z}_n(\underline{a} - \underline{b})$$

$$(\underline{Z}_n + 1)\underline{b} = (\underline{Z}_n - 1)\underline{a}$$

$$\underline{b} = (\underline{Z}_n + 1)^{-1}(\underline{Z}_n - 1)\underline{a}$$

$$\boxed{\underline{S} = (\underline{Z}_n + 1)^{-1}(\underline{Z}_n - 1) = (\underline{Z}_n - 1)(\underline{Z}_n + 1)^{-1}}$$

$$\underline{Z}_n = \underline{R}^{-\frac{1}{2}}\underline{Z}\underline{R}^{-\frac{1}{2}}$$

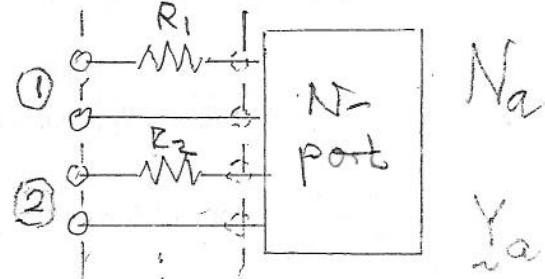
$$Z_{ij,n} = Z_{ij} / \sqrt{R_i R_j}$$

$$\rho = \frac{\underline{Z} - \underline{R}}{\underline{Z} + \underline{R}} = \frac{\underline{Z}_n - 1}{\underline{Z}_n + 1}$$

$$\underline{1} = \begin{bmatrix} 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \underline{Y}$$

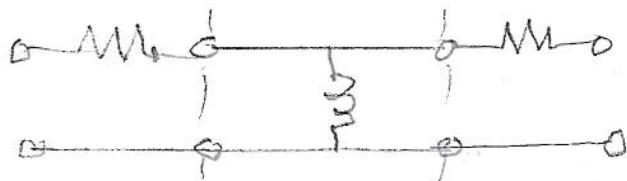
$$\underline{S} = (\underline{Z}_n - 1)(\underline{Z}_n + 1)^{-1} = (\underline{Z}_n + 1 - 2)(\underline{Z}_n + 1)^{-1}$$

$$= 1 - 2(\underline{Z}_n + 1)^{-1} = \underline{1} - 2\underline{Y}_{an}$$

(Normalized & augmented \underline{Y} matrix)As \underline{Y}_a , and hence \underline{Y}_{an} , always exists for any well-definedn-port, it means that \underline{S} also always exists.

$$\underline{Y}_n = \underline{R}^{1/2} \underline{Y} \underline{R}^{1/2}$$

$$Y_{n_{kl}} = Y_{kl} \sqrt{R_l R_k}$$

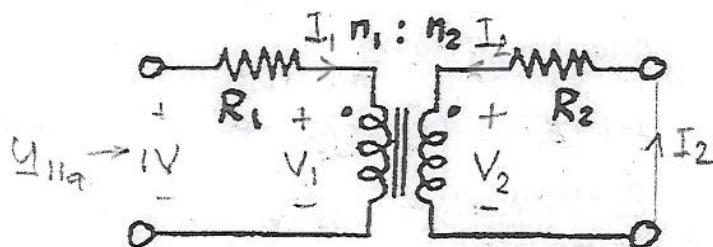


\underline{Y} doesn't exist,
but \underline{Y}_n does.

$$\underline{R}^{1/2} =$$

$$\begin{bmatrix} R_1^{1/2} & 0 & 0 & 0 \\ 0 & R_2^{1/2} & 0 & 0 \\ 0 & 0 & D & 0 \\ 0 & 0 & 0 & R_{kl}^{1/2} \end{bmatrix}$$

turns ratio

Examples $n : 1$ Ideal transformer $\frac{n_1}{n_2}$ turns
 n_1 turns
 n_2 ratio

$$V_1 = \frac{n_1}{n_2} V_2$$

$$I_1 = -\frac{n_2}{n_1} I_2$$

 $\underline{Y}, \underline{Z}$ not exist

$$\underline{Y}_a = \frac{1}{n_2^2 R_1 + n_1^2 R_2} \begin{bmatrix} n_2^2 & -n_1 n_2 \\ -n_1 n_2 & n_1^2 \end{bmatrix}$$

$$Y_{11a} = \frac{1}{R_1 + (\frac{n_1}{n_2})^2 R_2}$$

$$Y_{an} = \frac{1}{n_2^2 R_1 + n_1^2 R_2} \begin{bmatrix} n_2^2 R_1 & -n_1 n_2 \sqrt{R_1 R_2} \\ -n_1 n_2 \sqrt{R_1 R_2} & n_1^2 R_2 \end{bmatrix}$$

$$Y_{21a} = \frac{I_2}{V_1} \Big|_{V_2=0} = -\frac{n_1}{n_2} I_1$$

$$S = 1 - 2Y_{an} = \frac{1}{n_2^2 R_1 + n_1^2 R_2} \begin{bmatrix} n_1^2 R_2 - n_2^2 R_1 & 2n_1 n_2 \sqrt{R_1 R_2} \\ 2n_1 n_2 \sqrt{R_1 R_2} & n_2^2 R_1 - n_1^2 R_2 \end{bmatrix}$$

$$I_1 = Y_{11a}$$

$$I_2 = -\frac{n_1}{n_2} I_1 = \frac{-n_1/n_2}{R_1 + (\cdot)^2 R_2}$$

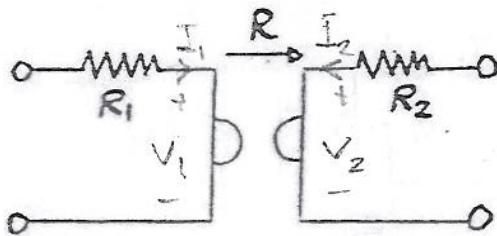
$$\text{If } \frac{R_1}{R_2} = \frac{n_1^2}{n_2^2} \quad \text{or} \quad n_1^2 R_2 = n_2^2 R_1$$

$$\text{Then } S = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$Y_{21a} = I_2 = Y_{12a}$$

$$Y_{22a} \quad 1 \leftrightarrow 2$$

Matched, lossless reciprocal circuit!

Gyrator

$$V_1 = Z_{11}I_1 + Z_{12}I_2$$

$$V_2 = Z_{21}I_1 + Z_{22}I_2$$

$$V_1 = -RI_2$$

$$V_2 = RI_1$$

$$\underline{Z} = \begin{bmatrix} 0 & -R \\ R & 0 \end{bmatrix}$$

$$\underline{Z}_{\text{an}} = \begin{bmatrix} R_1 & -R \\ R & R_2 \end{bmatrix}$$

$$\underline{Z}_g = \underline{Z} + \underline{R}$$

$$\begin{bmatrix} R_1 & 0 \\ 0 & R_2 \end{bmatrix}$$

If $R_1R_2 = R^2$ *nonreciprocal!*

$$\text{Then } \underline{S} = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

Note: We do not require $R_1=R_2=R$

Matched, lossless nonreciprocal circuit

$$\frac{1}{\underline{Z}} = \frac{1}{R^2 + R_1R_2} \begin{bmatrix} R^2 + R_1R_2 & 0 \\ 0 & R^2 + R_1R_2 \end{bmatrix}$$